

Modern Formal Methods for the Design and Verification of Complex Systems

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The ES Unit at FBK

Fondazione Bruno Kessler (FBK) is a research non-profit public interest entity, located in Trento, Italy.

The **Digital Industry** center focuses on digital technologies for various application domains (aerospace, railway, automotive, energy, agriculture, manufacturing, etc.)

- Research themes: Artificial Intelligence, Edge computing, Formal methods
- Research staff > 120, Director: Alessandro Cimatti

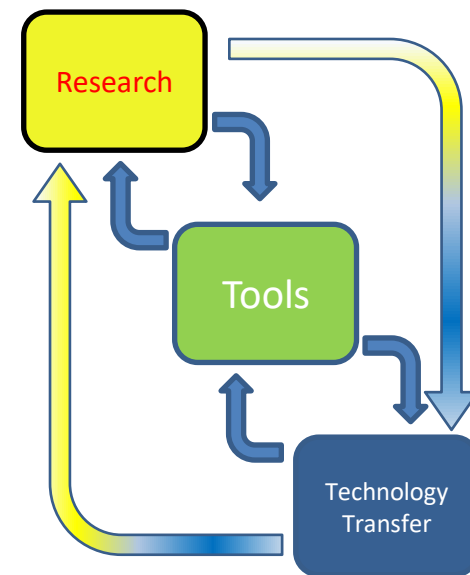
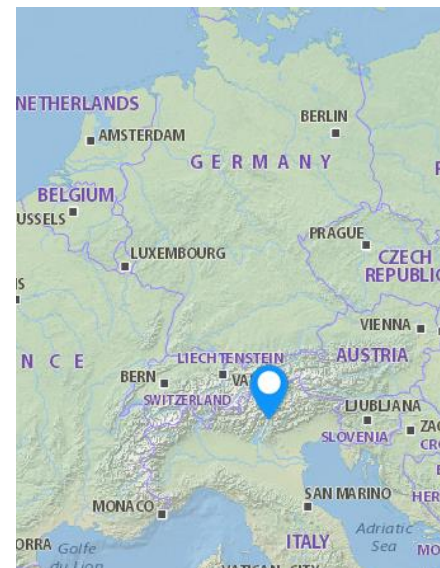
Strategy: strong synergy between basic Research, Tool development and Technology Transfer

Research Units

- Technologies for Vision, 3D Optical Metrology, Open IoT
- Data Science, Software Engineering, Machine Translation
- Embedded Systems
- People: >40, research staff, programmers, PhD students, technologists
- European projects: VALU3S, HUBCAP, AIPLAN4EU, AMASS, CITADEL, D-MILS, ...
- Technology transfer: RFI, Bosch, Boeing, NASA, Ansaldo, Intel, others under NDA
- Research focused on formal methods and automated reasoning

Topics:

- Model checking
- Requirements analysis
- Contract-based design
- Fault injection and safety analysis
- Fault detection, identification and recovery (FDIR)
- Planning
- Condition Monitoring
- Runtime verification



Goal and outline of the presentation

Goal:

- How can *modern* formal analysis techniques and tools support model-based design of complex systems

Outline of the talk:

- Formal verification
- Model-based safety assessment
- Contract-based design
- Comprehensive process/tool integration

Part 1: Functional Verification

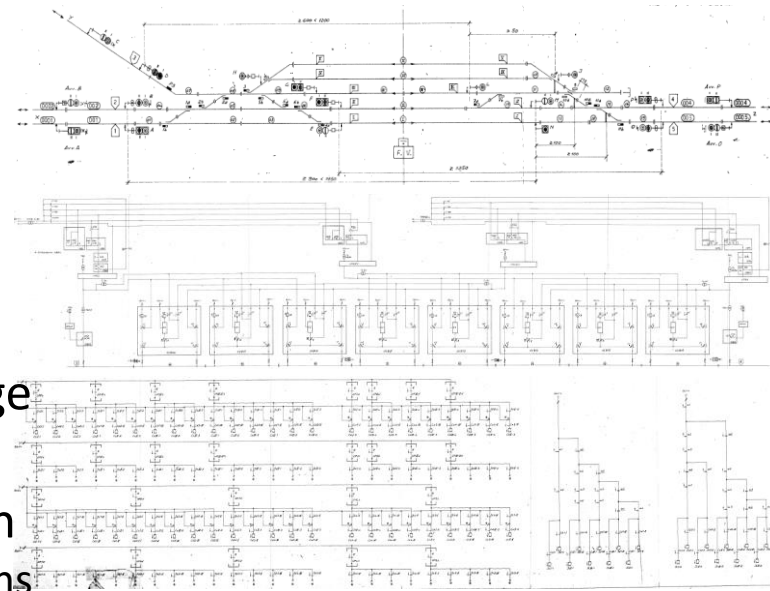
- Does **system satisfy Requirements**?
 - Systems modeled with a formal semantics
 - Requirements as properties in temporal logic
- System correctness reduced to formal reasoning in **mathematical** logic
- Model checking proves the property by means of state space exploration and deduction techniques
 - Fully **automated**
 - Explores **all** behaviors
 - Feedback as **counterexamples** or proofs
- Models? From netlists, RTL circuits, software, protocols, high-level languages

Modern Model Checking

- Increased **automation**: SAT-based verification
 - Based on Boolean reasoning, large capacity
 - Techniques: BMC, Induction, Interpolation, IC3
- Increased **expressiveness**: from SAT to SMT
 - Satisfiability Modulo Theories
 - Combining Boolean and mathematical reasoning
 - Timed and hybrid systems, RTL, microcode, software
- Fundamental role of **abstraction-refinement**
 - Implicit predicate abstraction
 - Incremental linearization
- Additional features
 - Proof production for certification
 - Parameter synthesis for design space exploration

A flagship application in the Railways domain

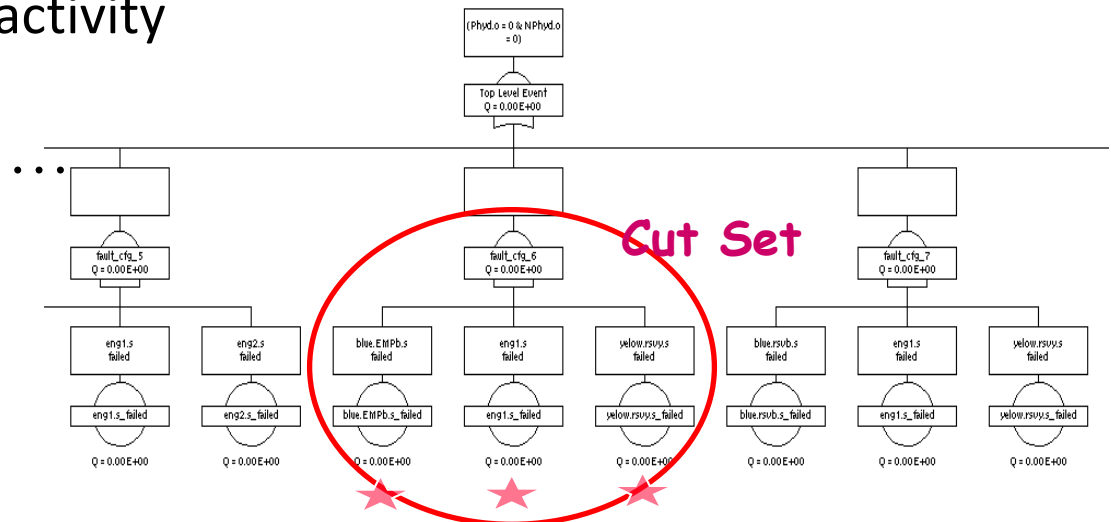
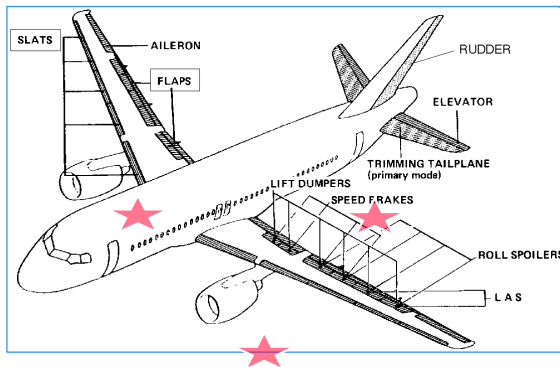
- New generation Station interlocking
- Two key objectives:
 - designing the **new solution**
 - dealing with the **legacy**
- Model-based design flow for new **computer-based** solution
 - Requirements in Structured Natural Language
 - Model checking of FSM and Software
 - Key challenge: dealing with parameterization
 - VV model: first V domain, second V's applications
- Legacy: **relay** interlocking systems
 - Complex modeling from circuit schematics
 - Compilation into hybrid automata
 - real time, clocks, electrical quantities
- Ongoing challenges
 - Relay-to-software traceability
 - Digitalization of legacy printouts



Part 2: Safety Assessment

Safety assessment

- How does a system respond to faults?
 - Hazard analysis, PASA/PSA, FTA, FMEA, CCA, ...
- Analysis of system behavior in presence of faults
 - Fault Tree Analysis (FTA)
 - Failure Modes and Effects Analysis (FMEA)
 - Common Cause Analysis (CCA)
- Typical problems
 - PB1: **misalignment** between design and SA, out of sync artifacts
 - PB2: **labor-intensive** activity

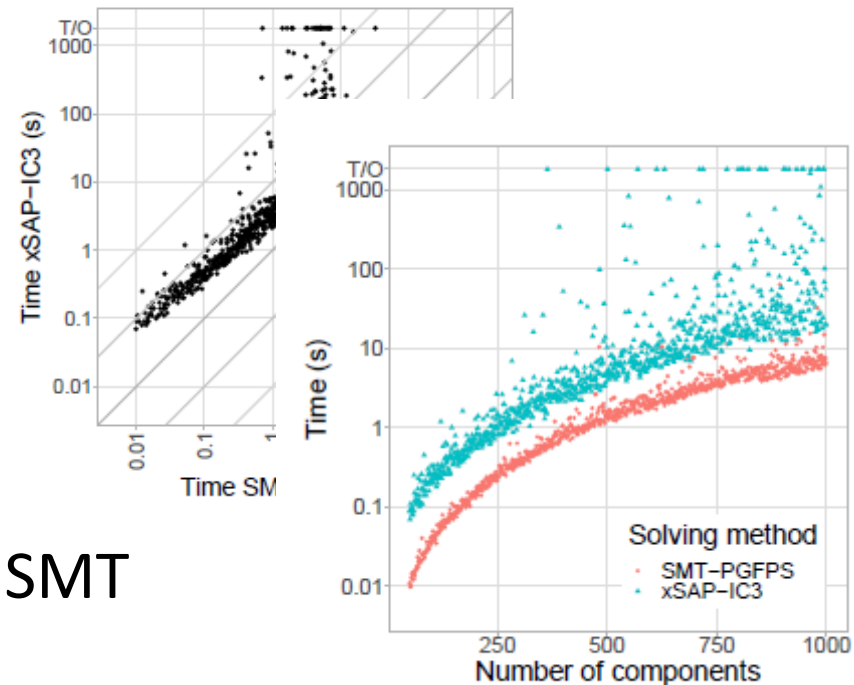
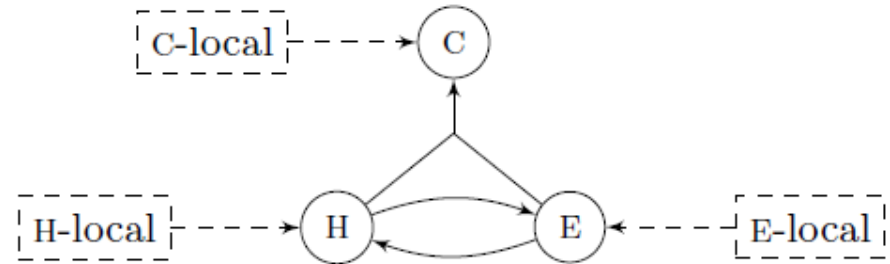


Model-based safety assessment

- Use formal techniques for modeling and analysis of **safety-related aspects**
- Model includes non-nominal, faulty behaviors
 - Fault variables trigger **non-nominal behaviors**
 - Use model checking techniques for automation
- Automated techniques for **minimal cut set** analysis
 - collect configuration of assignments to fault variables causing the feared (top-level) event
 - TLE as violation of the requirement
 - Extract minimal cut set, iterate
 - Results: fault trees, FMEA tables, reliability measures

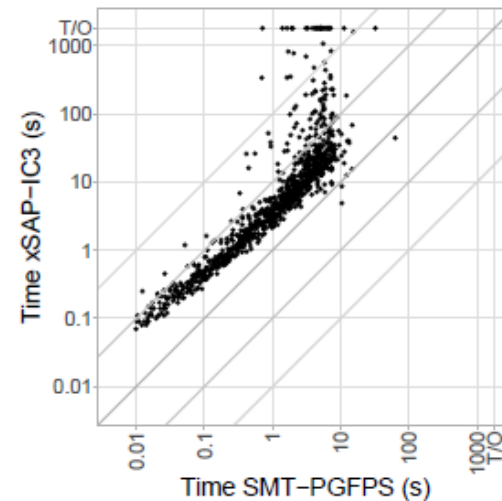
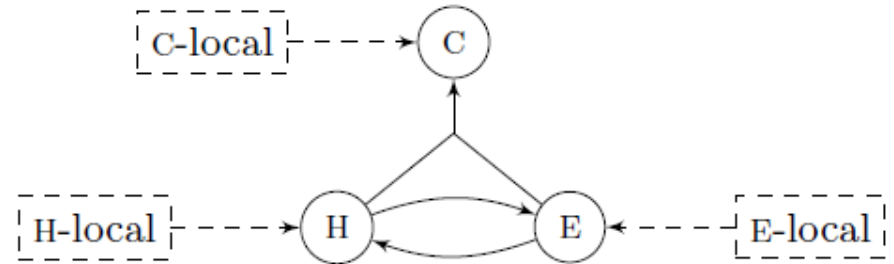
High-level Propagation Analysis

- Abstract view of subsystems
 - endogenous failures
 - propagated failures
 - and-or dependencies
- Challenges
 - Complex fault models
 - Cyclic structures
 - Timing dependencies
 - Mode dependencies
- Scalability?
 - Sequential semantics
 - Reduction to combinational SMT yields great speed-ups



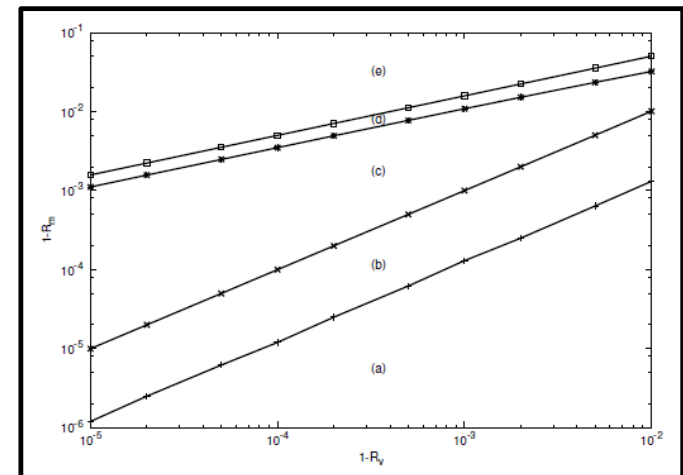
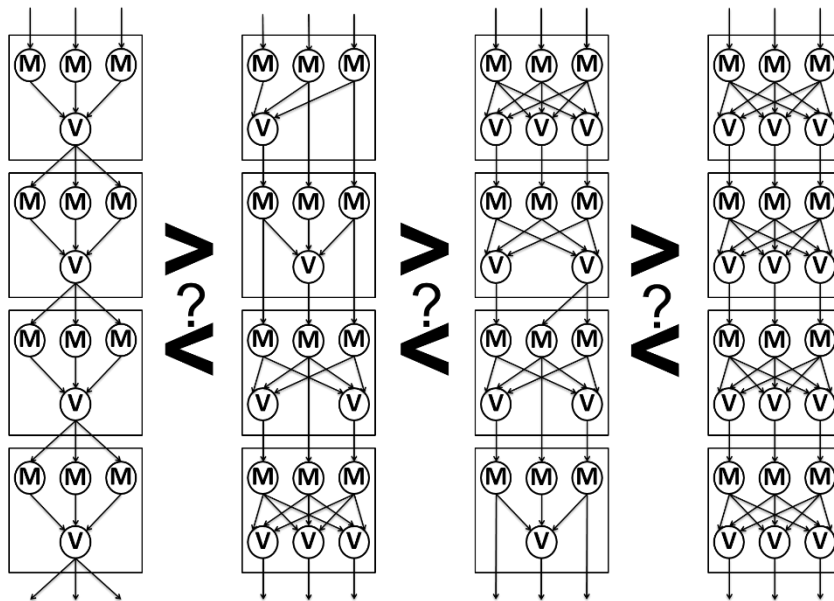
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Reliability Analysis of Redundancy Architectures

- Does a solution based on redundancy (e.g. TMR) help?
 - SMT-based techniques for cut-set analysis
 - Symbolic Reliability computation
- Design-Space Exploration
 - assess quality of deployment configurations
 - find best deployment configuration
 - multi-objective optimization
 - cost, weight, power, reliability



Behavioral Model-Based Safety Analysis

- Start from model of nominal behaviors
- Automatically inject faults
 - Fault-extension directives
 - Library-based approach
- Formal Analyses of extended system model
 - Fault Tree Analysis (FTA)
 - Failure Modes and Effects Analysis (FMEA)
 - Common Cause Analysis (CCA)
- PB1? Extended model **aligned by construction** to nominal model!
- PB2? Model checking engine ensures **scalability!**

Model-Based Safety Analysis

MODULE power_system_unit

VAR

gen1: generator; gen2: generator;
voltage_out : real;

ASSIGN

voltage_out := case
gen1.voltage_out >=
gen2.voltage_out: gen1.voltage_out;

TRUE: gen2.voltage_out;

esac;

Nominal model

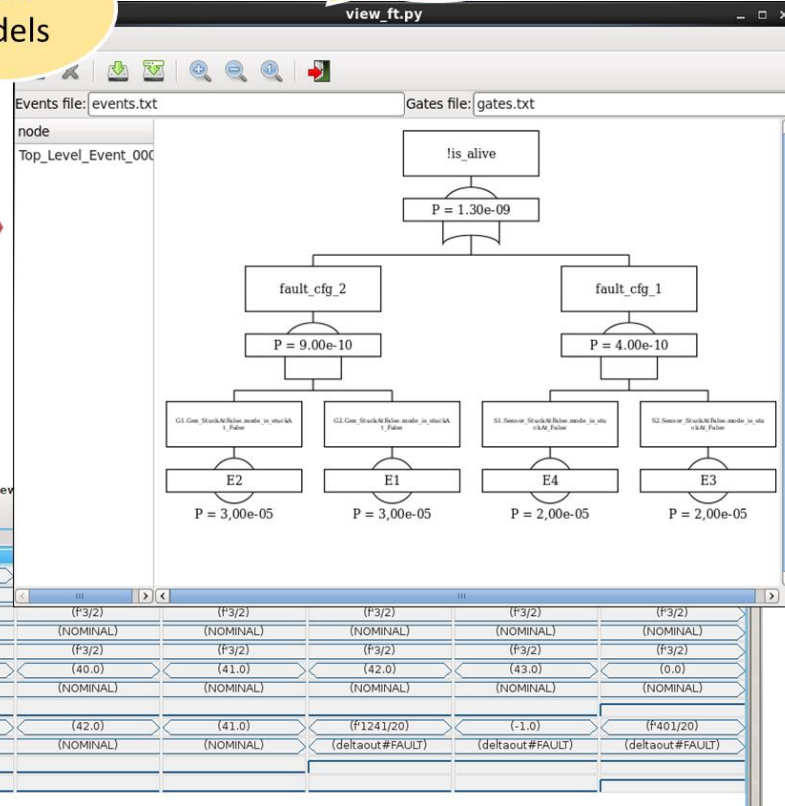
EXTENSION OF MODULE generator

-- Description of Fault Slice
generator_failure --/

SLICE generator_failure AFFECTS
voltage_out WITH
MODE rampdown {1.5e-6} : Permanent
ampDown(
data decr << 0.1,
data end_value << 0.0,
data input << voltage_out,
data varout >> voltage_out,
event failure);

Fault models

Fault trees



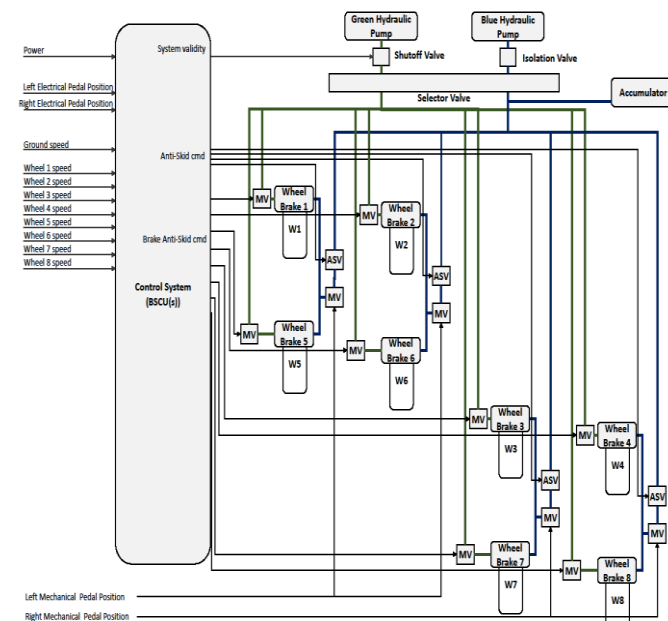
Counter Example Trace View

Name	Step1	Step2	Step3	Step4
batt1.battery_failure.mode	(NOMINAL)	(rampdown#FAULT)	(rampdown#FAULT)	(rampdown#FAULT)
batt1.voltage_out	(F3/2)	(F3/2)	(F7/5)	(F13/10)
batt2.battery_failure.mode	(NOMINAL)	(NOMINAL)	(NOMINAL)	(NOMINAL)
batt2.voltage_out	(F3/2)	(F3/2)	(F3/2)	(F3/2)
gen.generator_failure.mode	(NOMINAL)	(NOMINAL)	(NOMINAL)	(NOMINAL)
gen.voltage_out	(F3/2)	(F3/2)	(F3/2)	(F3/2)
s1.reading	(40.0)	(39.0)	(38.0)	(39.0)
s1.sensor_failure.mode	(NOMINAL)	(NOMINAL)	(NOMINAL)	(NOMINAL)
_S1_WRONG				
s2.reading	(40.0)	(41.0)	(40.0)	(41.0)
s2.sensor_failure.mode	(NOMINAL)	(NOMINAL)	(NOMINAL)	(NOMINAL)
_S2_WRONG				
_SYSTEM_FAILURE				

Traces

AIR6110 Wheel Brake System

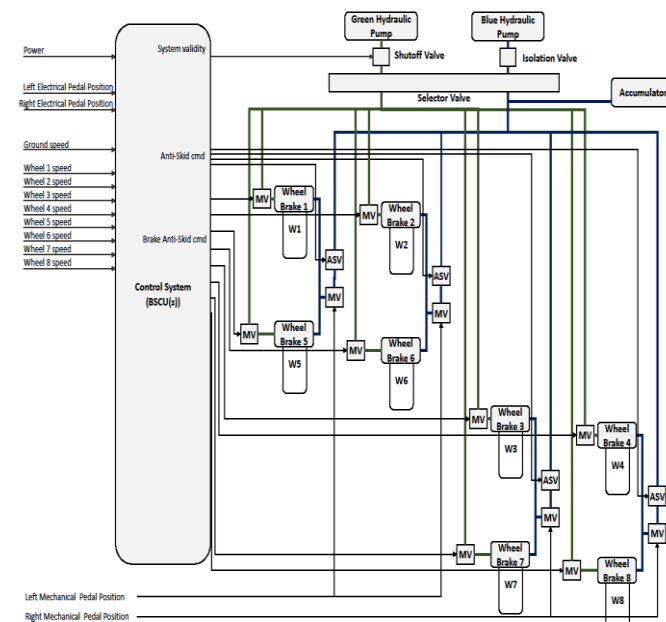
- Aerospace Information Report 6110:
 - Traditional Aircraft/System Development Process Example
 - Describes the development process of a Wheel Brake System for a fictional dual-engine aircraft
 - Analyzes different architectures with standard informal techniques
- Objectives:
 - Analyze the system safety through formal techniques
 - Repeat AIR6110 steps with formal techniques to demonstrate the usefulness and suitability of formal techniques for improving the overall traditional development and supporting aircraft certification
- Main features of the system
 - Control brake for aircraft wheels
 - Redundancy
 - Multiple BCSU
 - Hydraulic plants
 - Functions
 - Asymmetrical braking
 - Antiskid (single wheel/coupled, depending on control mode)
- Review of the AIR6110 with:
 - Formal modeling
 - Formal Verification & Validation
 - Formal Safety Assessment



AIR6110 Wheel Brake System

- Aerospace Information Report 6110:
 - Traditional Aircraft/System Development Process
 - Describes the development process for a fictional dual-channel system
 - Analyzes differences
- Objectives
 - Analyze
- Main results
 - Control strategy
 - Redundancy
 - Multiple ESU
 - Hydraulic plants
 - Functions
 - Asymmetrical braking
 - Antiskid (single wheel/coupled, depending on control mode)
- Review of the AIR6110 with:
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“Automated Fault Extension results in tremendous increase in productivity”

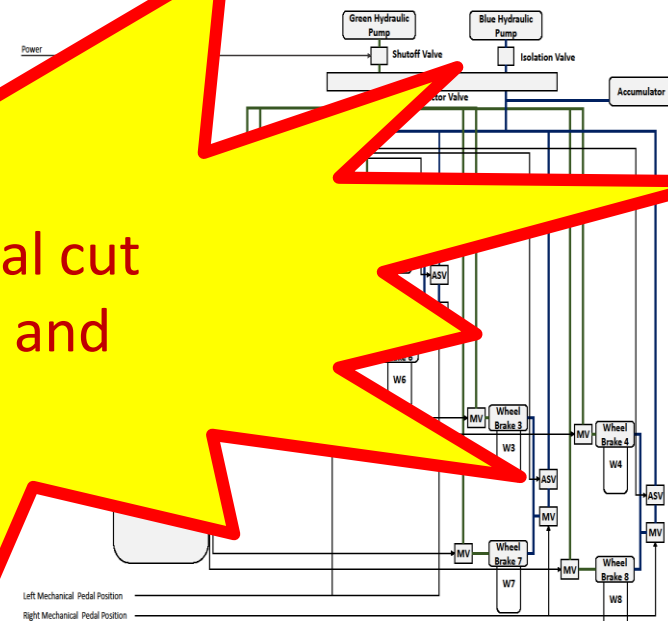


AIR6110 Wheel Brake System

- Aerospace Information Report 6110:
 - Traditional Aircraft/System Development Process
 - Describes the development process for a fictional dual-channel system
 - Analyzes differences
- Objectives
 - Analyze
- Main Results
 - Control Strategy
 - Redundancy
 - Multiple ESU
 - Hydraulic plants
 - Functions
 - Asymmetric
 - Antiskid (single)
- Review of the AIR6110 v.1.0
 - Formal
 - Formal Verification
 - Formal Safety Assessment

“Automated Fault Extension results in tremendous increase in productivity”

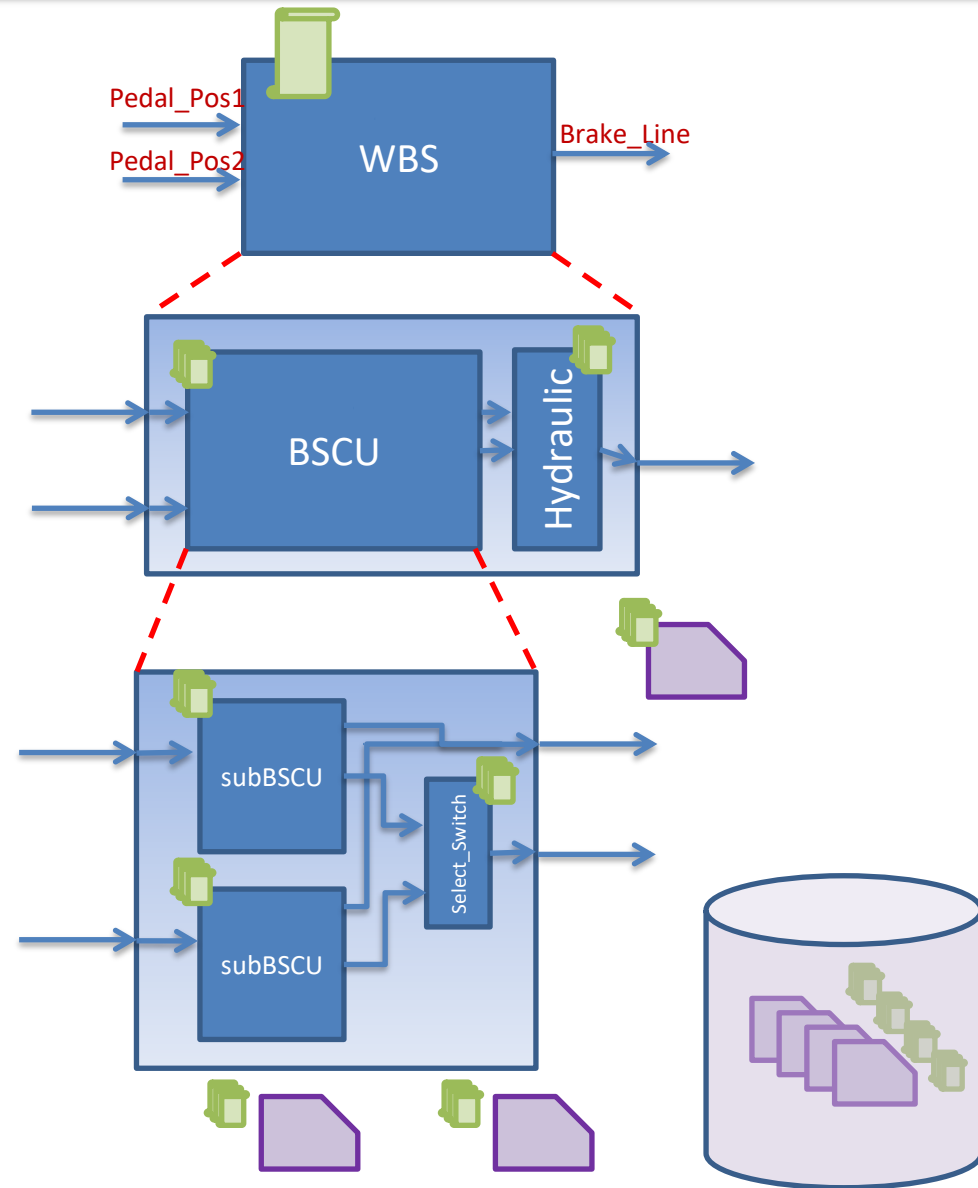
$O(100K)$ minimal cut sets, degree 7 and above



Part 3: Contract-Based Design

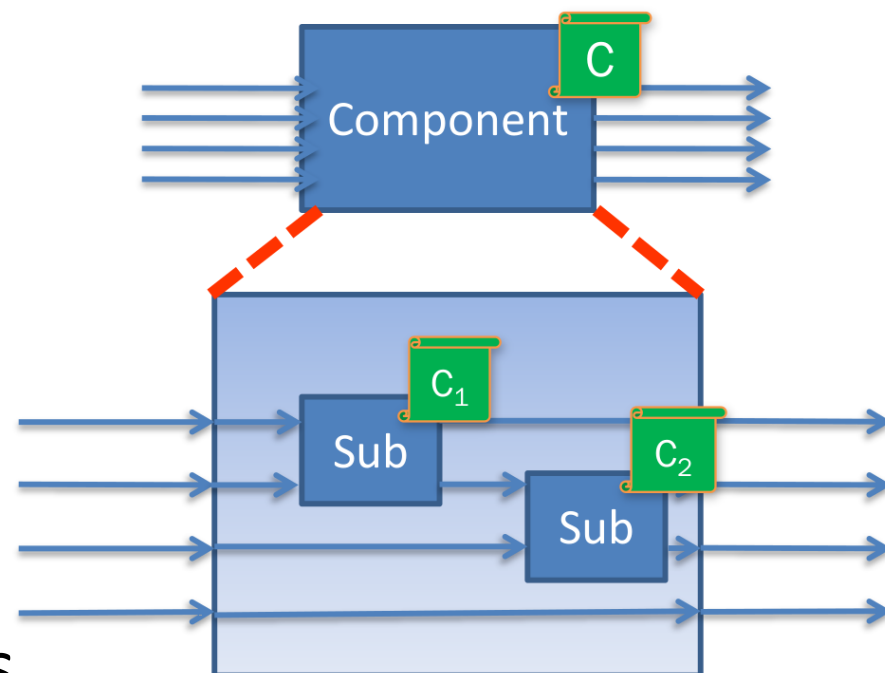
Contract-based design

- Contracts used to specify assumptions and guarantees
 - First conceived for software, now popular also for **system architectural design**
- Assumptions and guarantees are properties respectively of the environment and of component
- Can be seen as assertions for component interfaces.
- Contracts used for:
 - Early validation of refinement
 - Composition verification
 - Ensuring correct reuse



Contract-refinement Calculus

- Component decomposed into connection of subcomponents
- Contracts $\langle A, G \rangle$ as temporal logic formulae, written in controlled natural language
- Top level contract follows from contracts of subcomponents
 - $C_1 \ \& \ C_2 \ \rightarrow \ C$



- Assumptions on component must be satisfied
 - $A \ \& \ C_1 \ \& \ \dots \ \& \ C_{n-1} \ \rightarrow \ A_n$

Contract-Based Verification of Automotive Software

- Ongoing joint project w/ Evidence
- Integration of contract-based design within Huawei AUTOSAR design environment
- Translation of **Architecture** to OCRA diagrams
 - Contract editing
 - Refinement verification
 - Direct mapping on FBK contract-based design tool OCRA
- Behavioral Analysis of **Components**
 - Does runnable satisfy contracts?
 - Runnables verification via software model checking
 - Direct mapping on FBK software model checker KRATOS

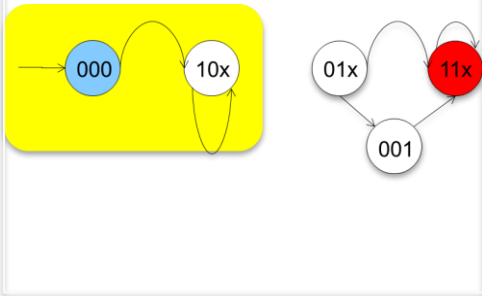
Part 4:

Comprehensive Integration within the design flow

- FBK MBD tools for model checking, safety assessment and contract-based design have been harmonized and integrated into various AADL- and SysML-based modeling environments:
 - AF3, COMPASS, CHESS, CAMEO
- Integration requires:
 - Extension for needed modeling elements (contracts, fault injection, etc.)
 - Semantic-preserving translation
 - Mapping back of results

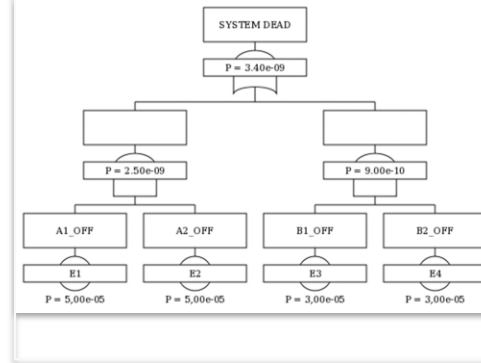
Integrated Design Environment

EST – common integration interface



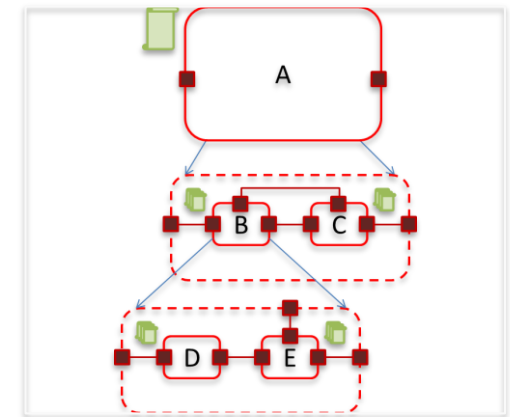
nuXmv, kratos, hycomp, ...

Model checking



xSAP

Model-based safety analysis

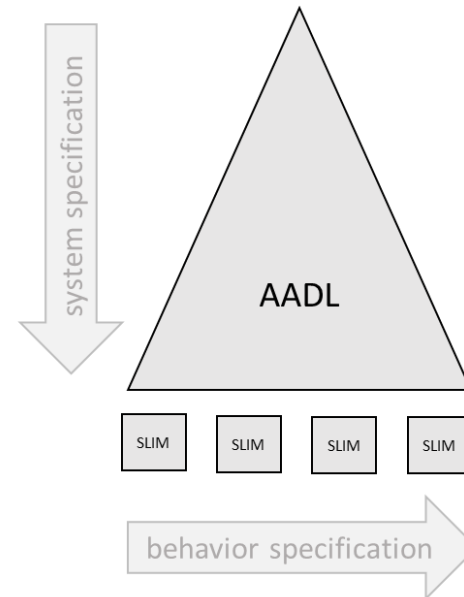


OCRA

Contract-based design

COMPASS: verification + contracts + safety assessment

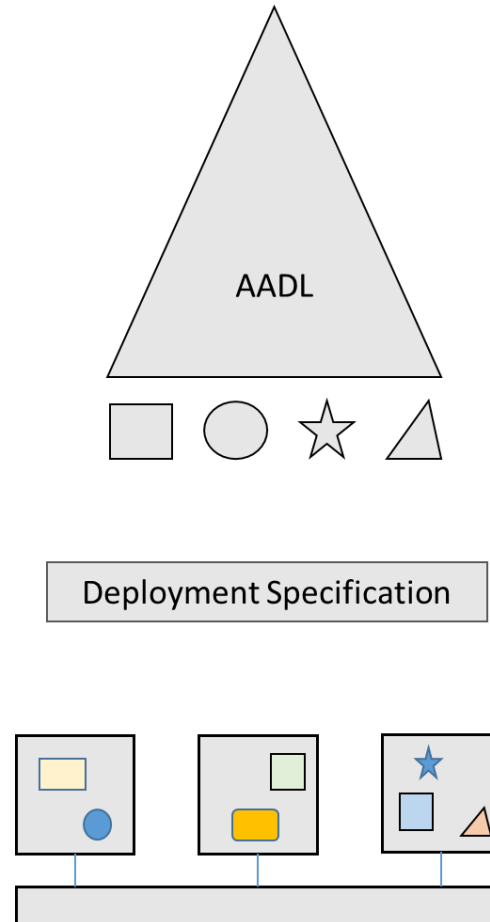
- Toolset for model-based system/SW co-engineering
- Developed in a series of ESA studies (2008-2016)
- Based on a variant of AADL (SLIM)
- Formal design , V&V
 - Requirements specification and analysis
 - Contract-based design
 - Functional verification
 - Fault injection, model extension
 - Safety assessment and dependability, FDIR
- Based on model checking
- Latest release: COMPASS 3.1 (2019)



- Model checking
- Requirements analysis
- Contract-based design
- Fault injection
- FTA/FMEA
- FDIR
- Performability analysis

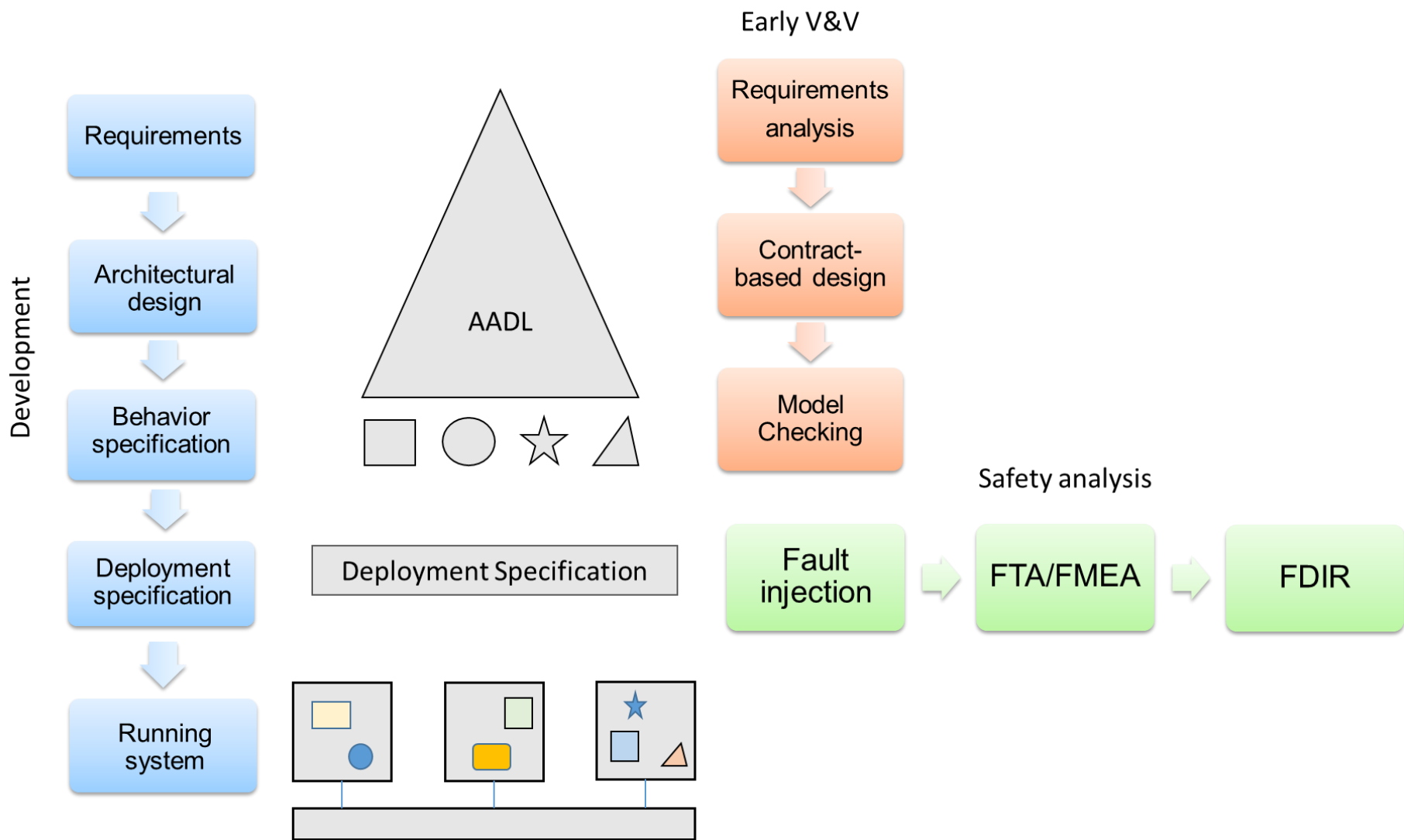
TASTE: model-based design + run-time deployment

- Development environment dedicated to model-based design of embedded, real-time systems
- Created by initiative of ESA in 2008
- Modeling languages
 - AADL for the functional logical architecture (Interface view description)
 - ASN.1 for data abstraction and implementation
 - SDL, Simulink, VDM, ... for behavior specification
 - AADL for the physical architecture (Deployment view description)
- Tools: graphical editors, visualizers, code generators and middleware
 - Code generation to C, Ada, supported in the OpenGeode editor and tools such as QGen



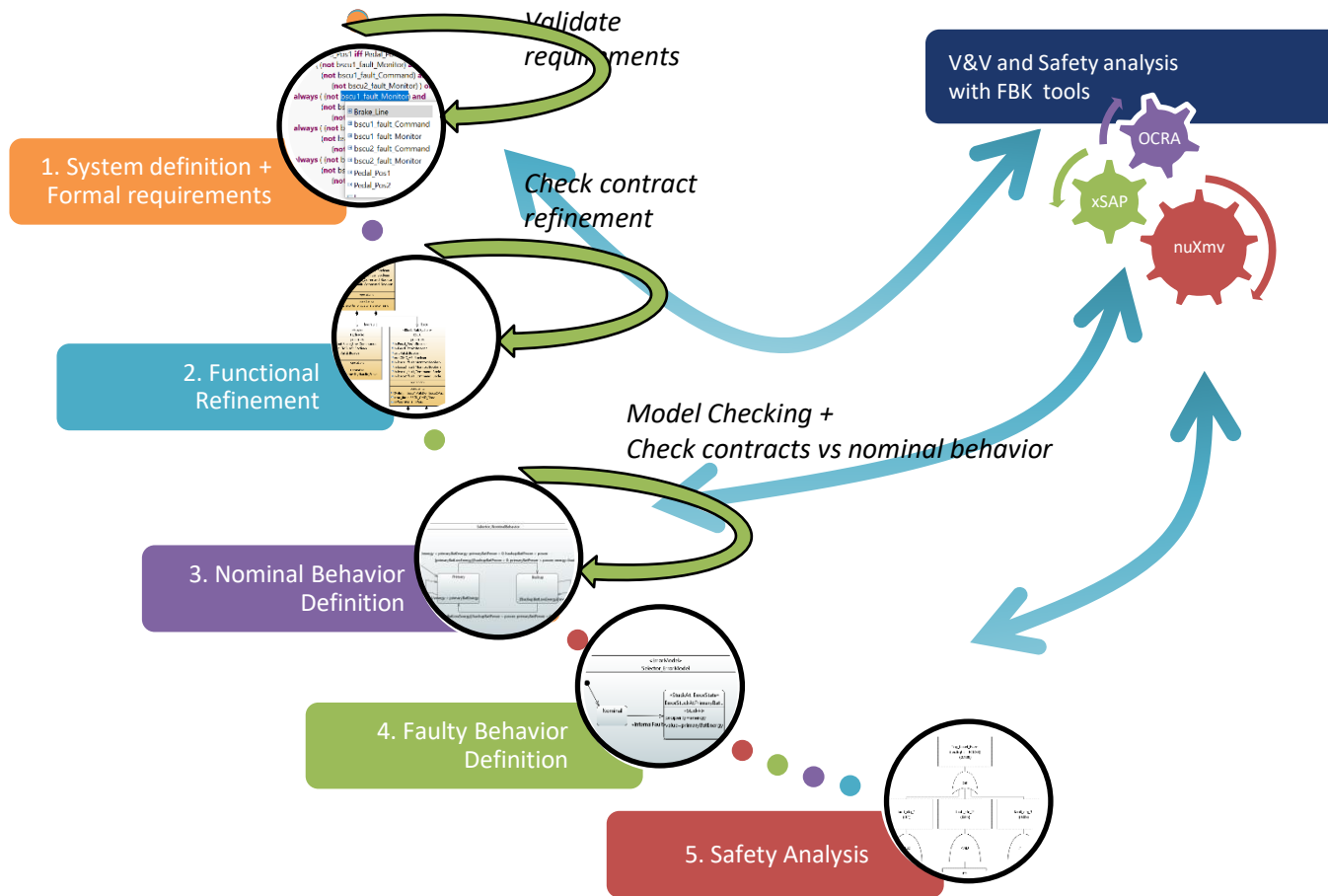
- Many languages (behavior)
- Push-button compilers to deployment
- Graphical editor for AADL
- Graphical editor for SDL
- Integrability via generation of DB, GUI and Python

COMPASS+TASTE: integrating the whole flow!



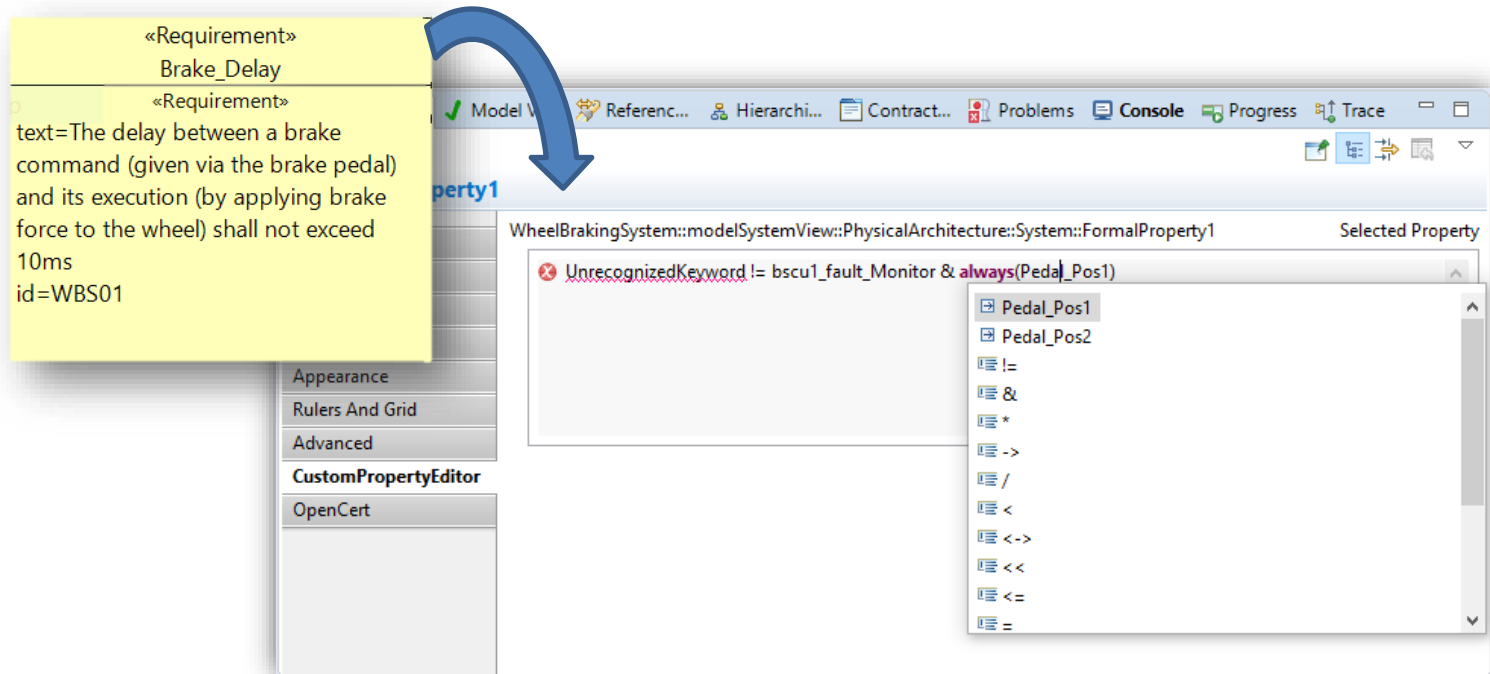
- Model-Based Design of Safety Critical Systems
- UML/SysML diagrams (Papyrus) extended with stereotypes for analysis: formal properties, contracts, error models, etc.
- Analysis supported by backend tools including nuXmv, xSAP, and OCRA
- Implemented in Java and Eclipse
- Open source supported by Eclipse community
- Currently mainly contributed by Intecs and FBK

Architecture Design in CHESS



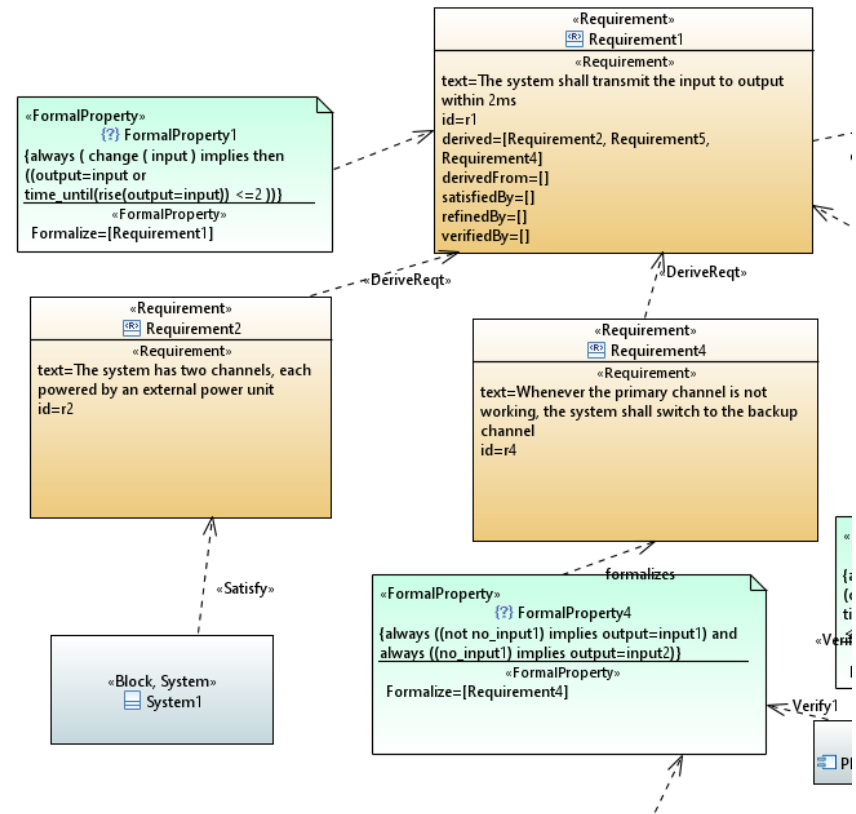
System Design: Requirement Formalization

- Informal requirements represented in SysML Requirements Diagram
 - imported from excel files, csv files, or by using the ReqIF
- Formalized into LTL properties (new stereotype FormalProperty)
 - textual editor with content assistant



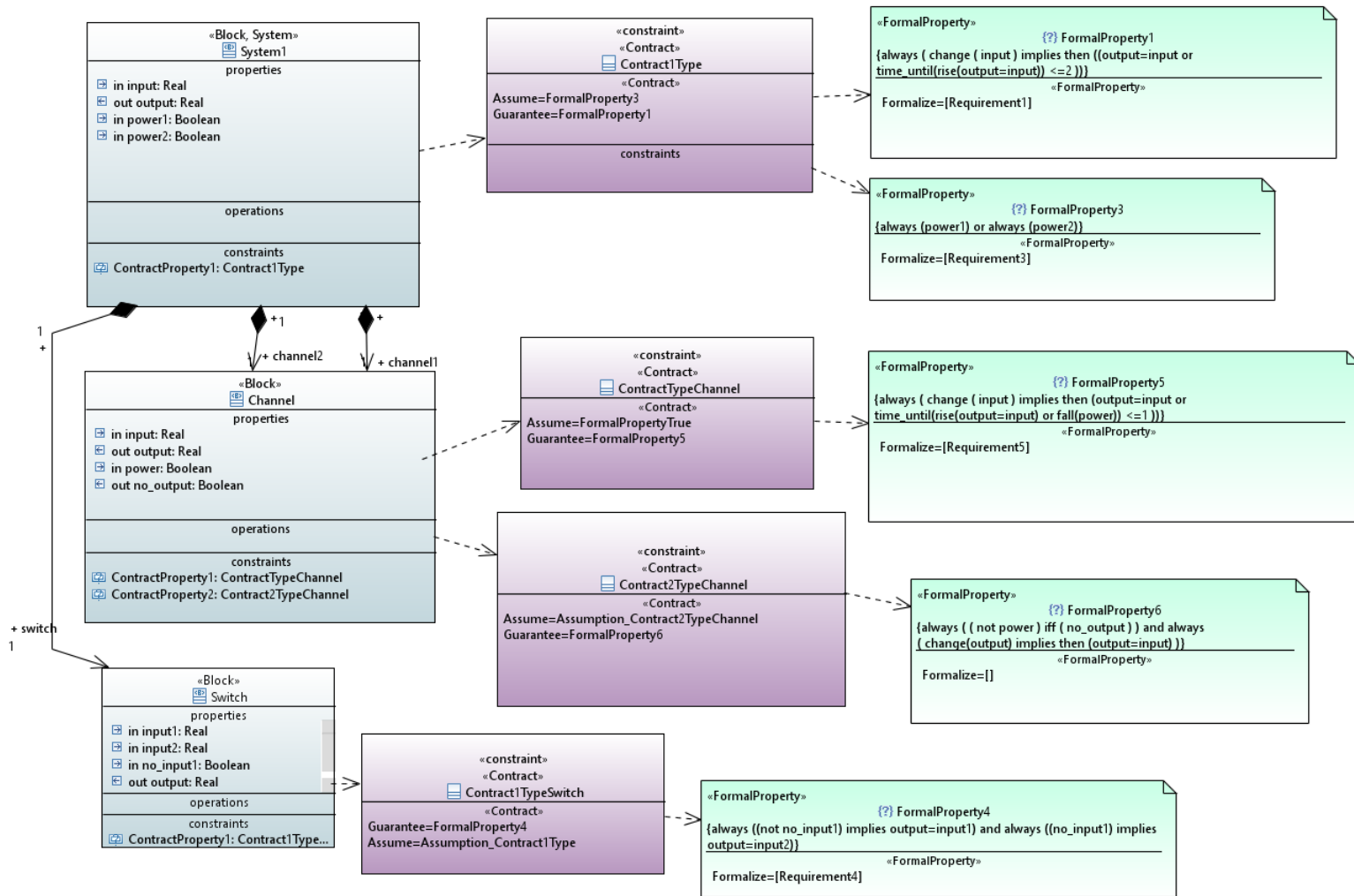
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 - imported from excel files, csv files, or by using ReqIF
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 - new stereotype FormalProperty
 - textual editor with content assistant
- Requirements diagrams used also to track allocation to components and analysis results



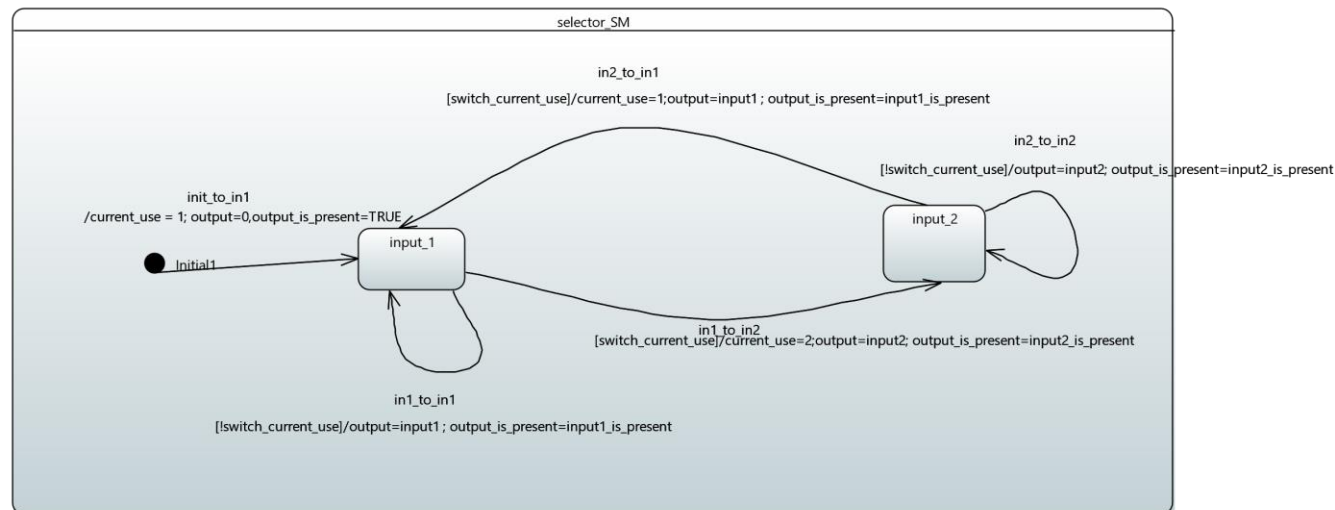
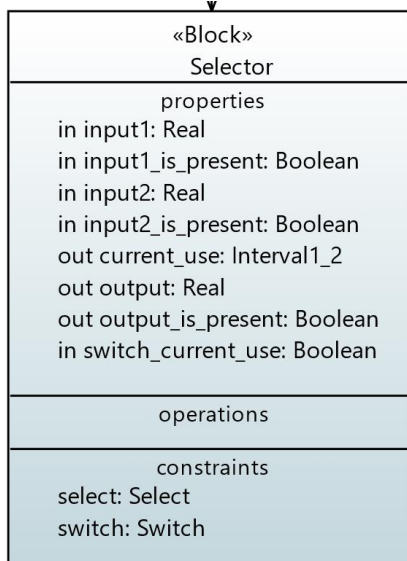
System Design: Architectural Refinement

- SysML Block Diagrams extended with contracts



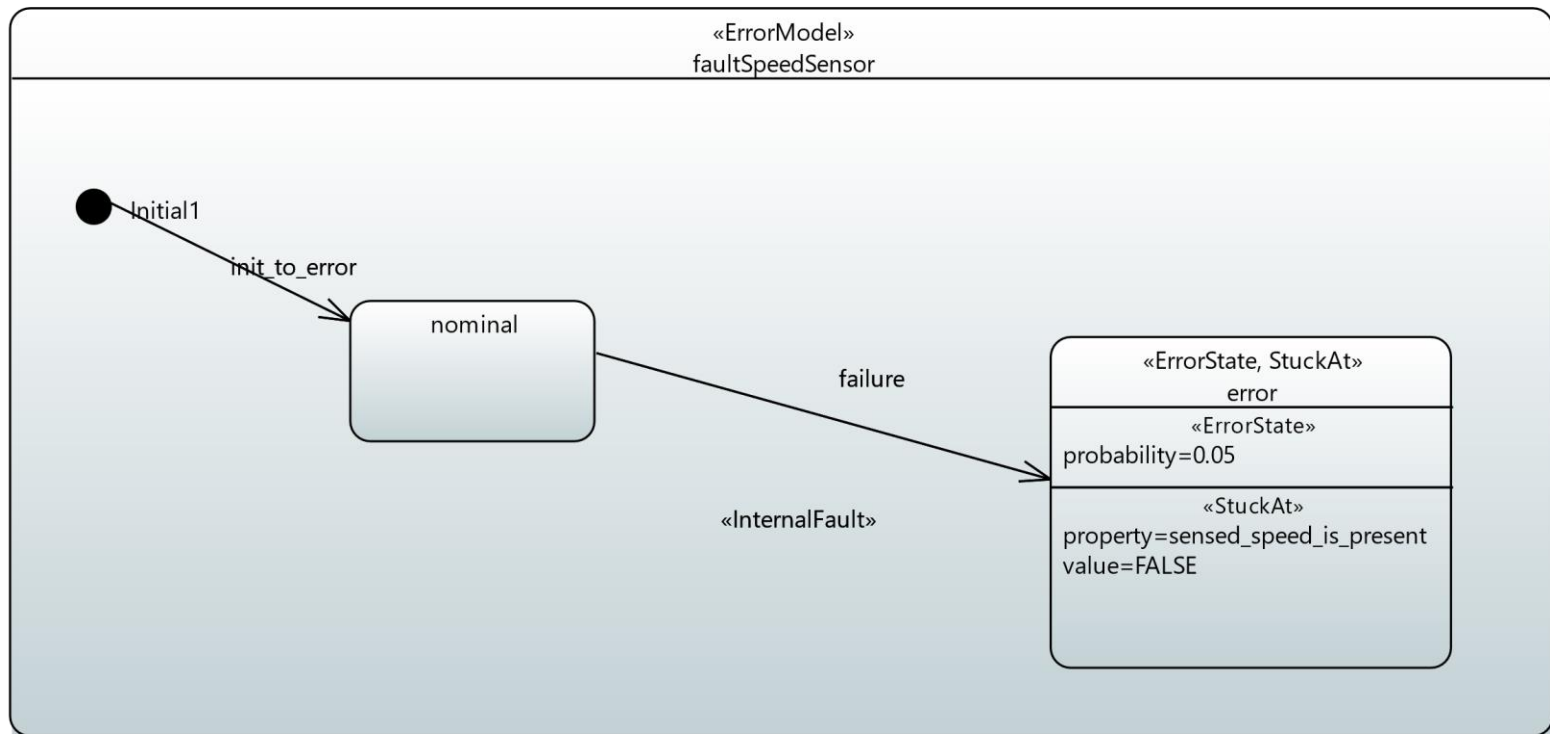
System Design: Nominal Behavior Definition

- SysML State Machine Diagrams are used to model the nominal behavior definition of the component.
- A transition comes with a guard and an effect. The guard is a boolean condition upon the values of components properties.



System Design: Faulty Behavior Definition

- Faults are introduced into the system (Fault injection)
- SysML State Machine Diagrams are used to model the faulty behavior definition of the component.



Wrapping up

- Beyond traditional formal methods
 - Does system satisfy requirements
 - Automated abstraction: huge scalability improvements
- Contract-based design
 - formal counterpart of compositional design
 - contracts, contract refinement
 - compositional proofs, parallelization
- Model-based Safety Assessment
 - Does system properly deal with faults
 - Propagation analysis: high-level fault propagation graphs
 - Redundancy analysis
 - Behavioral view: fault injection
- Overarching integration and tool support
- Several practical applications

Future challenges

- Verification of AI-based systems
 - Does system satisfy requirements
 - Automated abstraction: huge scalability improvements
- Tighter integration of Safety Assessment phases
 - from PASA/PSA to behavioral analysis
 - Hierarchical fault trees
- Contract-based design
 - Contract-based Safety Assessment
 - Contract synthesis/discovery
- Hiding formal within traditional design flow

Thanks for your attention

Questions?